# Bayesian Optimization for Hyperparameter Optimization

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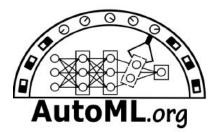
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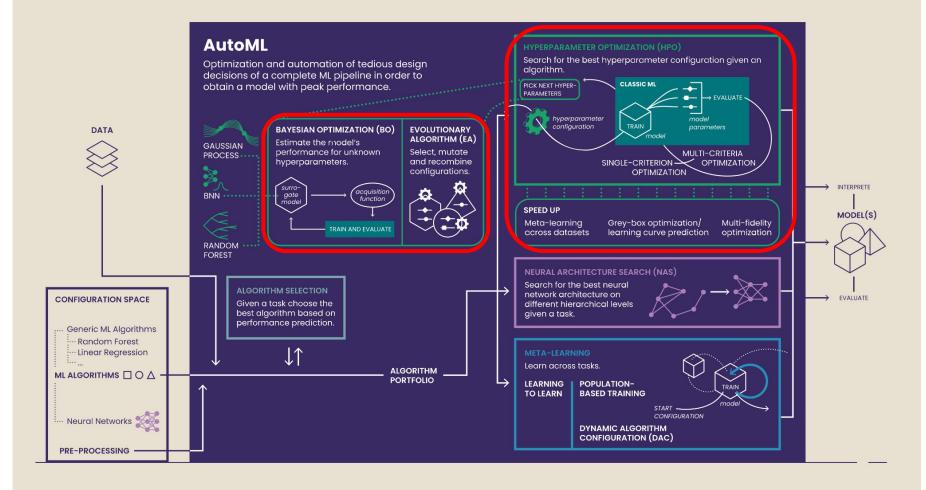




# Questions?

Let's use sli.do. Please use "Day 2"!

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## Story Line Today

- What do we optimize?
  - Parameters vs. Hyperparameters
  - Challenges for AutoML
- How do we optimize it?
  - Grid Search
  - Random Search
- How do we optimize it efficiently?
  - Bayesian Optimization
- How do we optimize it even more?
  - Multi-Fidelity Optimization using Hyperband
  - Multi-Objective Optimization using ParEGO
- Demo: SMAC



Note: This lecture is based on the free online lecture "Automated Machine Learning" at <u>https://learn.ki-campus.org/courses/automl-luh2021</u>

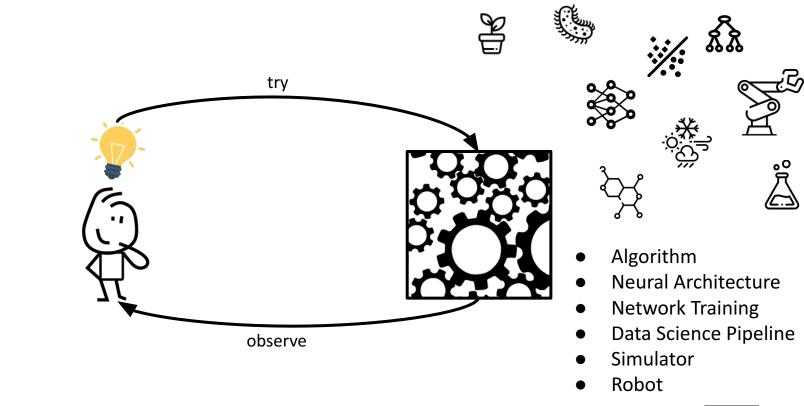
- Basics of HPO
- Bayesian Optimization for HPO
- Speedup Techniques for Hyperparameter Optimiziation
- Multi-criteria Optimization



## What do we optimize?

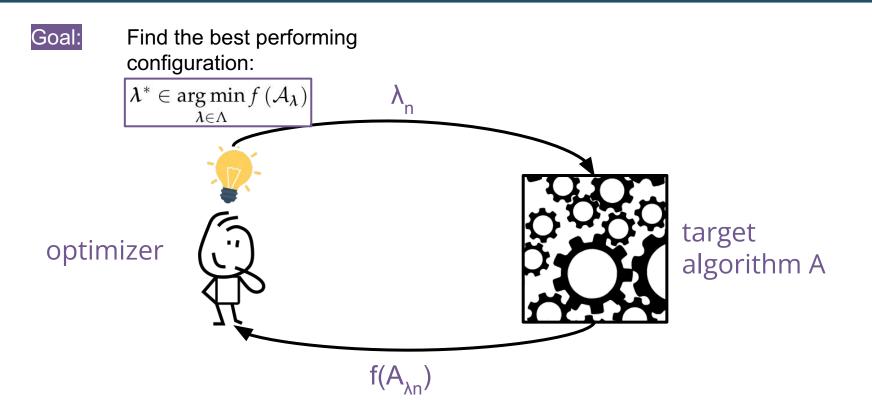
>> Here's my algorithm and data, what should I do?

## **Sequential Experimentation**





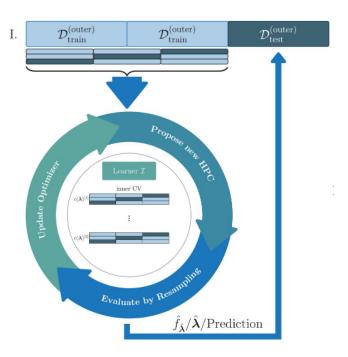
## Hyperparameter Optimization





#### Example

- **Given a dataset**, we want to train a neural network
- We need to choose a learning rate and architecture
- The "learner" takes the input data, and returns a fitted network
- →We are interested in generalization error!
- → We need to look at how our trained model **performs** on "unseen" data
- $\rightarrow$  We evaluate different settings and select the one that **performs best w.r.t generalization error**.



#### Image: Bischl et al. 2023



**Model parameters** can be optimized during training and are the output of the training. Examples:

- Splits of a Decision Tree
- Weights of a Neural Network
- Coefficients of a linear model

**Hyperparameters** need to be set manually before training. They control the flexibility, structure and complexity of the model and training procedure. Examples:

- Max. depth of a Decision Tree
- Number of layers of a Neural Network
- K for K-Nearest Neighbours



## Types of Hyperparameters

#### **Real-valued**

- Learning rate for SGD to train NNs
- Bandwidth of kernel density estimates in Naive Bayes

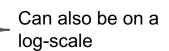
#### Integer

- #Neurons in a layer of a NN
- maximum depth of a Decision Tree

#### Categorical

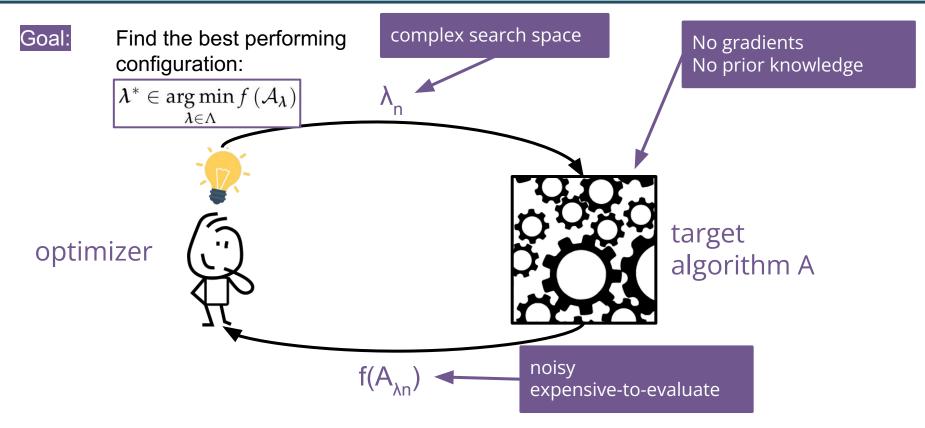
- Training Algorithm for NNs
- Split criterion for Decision Trees

+ Hyperparameters can be hierarchically dependent on each other





## Why is Hyperparameter Optimization Challenging?

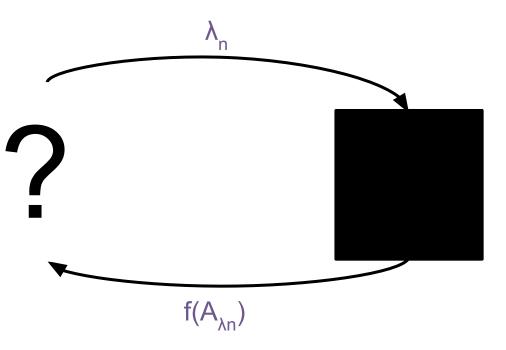




## How do we optimize it?

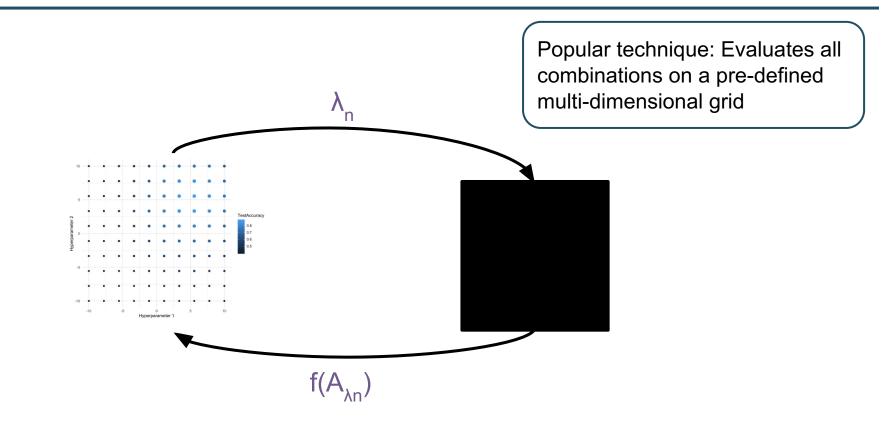
>> Here's my algorithm, data, metric and search space, what should I do?

## **Black-Box Optimization Problem**



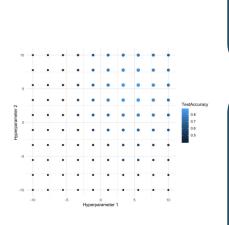


#### **Option 1: Grid Search**





## **Option 1: Grid Search II**



#### **Advantages**

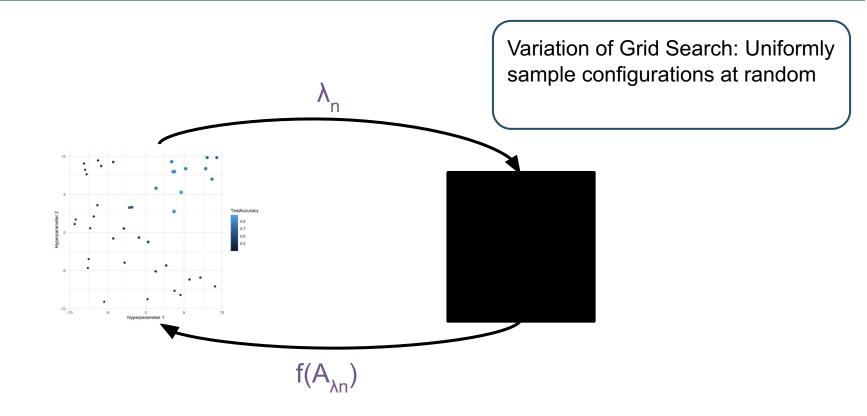
- Very easy to implement
- Very easy to parallelize
- Can handle all types of hyperparameters

#### Disadvantages

- Scales badly with #dimensions
- Inefficient: Searches irrelevant areas
- Requires to manual define discretization
- All grid points need to be evaluated

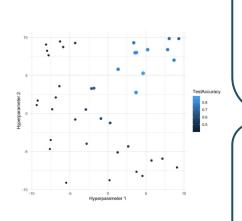


#### **Option 2: Random Search**





## **Option 2: Random Search II**



#### **Advantages**

- Very easy to implement
- Very easy to parallelize
- Can handle all types of hyperparameters
- No discretization required
- Anytime algorithm: Can be stopped and continued based on the available budget and performance goal.

#### **Disadvantages**

- Scales badly with #dimensions
- Inefficient: Searches irrelevant areas



#### Grid Search vs. Random Search

With a **budget** of T iterations:

**Grid Search** evaluates only  $T^{\frac{1}{d}}$  unique values per dimension

Random Search evaluates (most likely) T different values per dimension

 $\rightarrow$  Grid search can be disadvantageous if some hyperparameters have little of no impact on the performance [Bergstra et al. 2012]

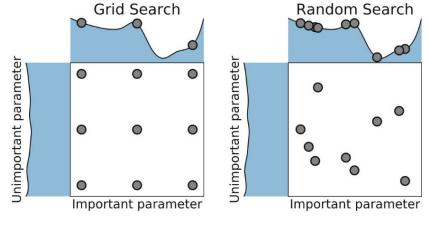


Image source: [Hutter et al. 2019]





# Questions?

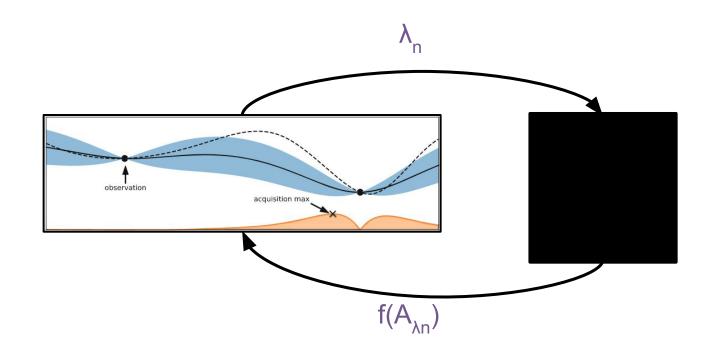
# Kahoot Quiz I

## How do we optimize it efficiently?

>> Here's my algorithm, data and design space and I have only limited time, what should I do?

#### Model-based Optimization

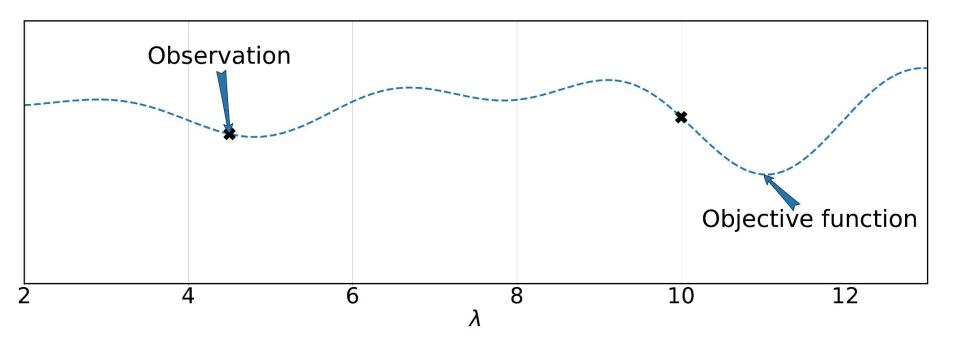
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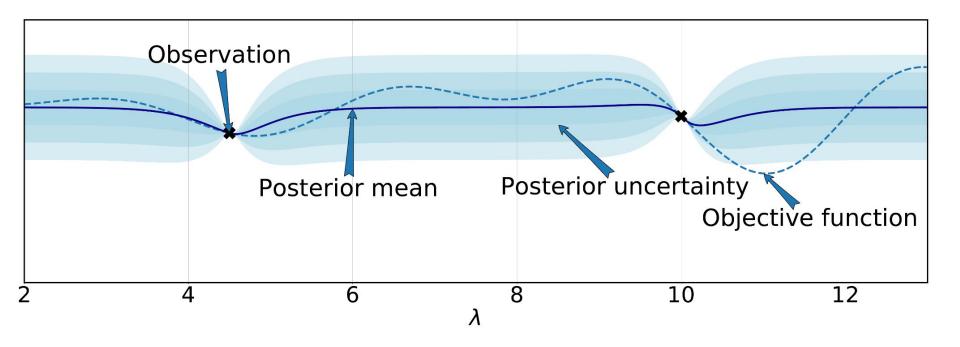


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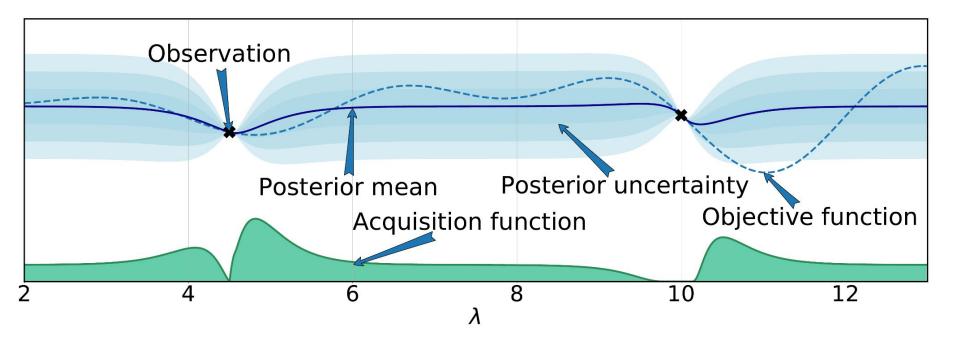
Photo by <u>Wilhelm Gunkel</u> on <u>Unsolash</u> Image by Feurer, Hutter: Hyperparameter Optimization. In: Automated Machine Learning



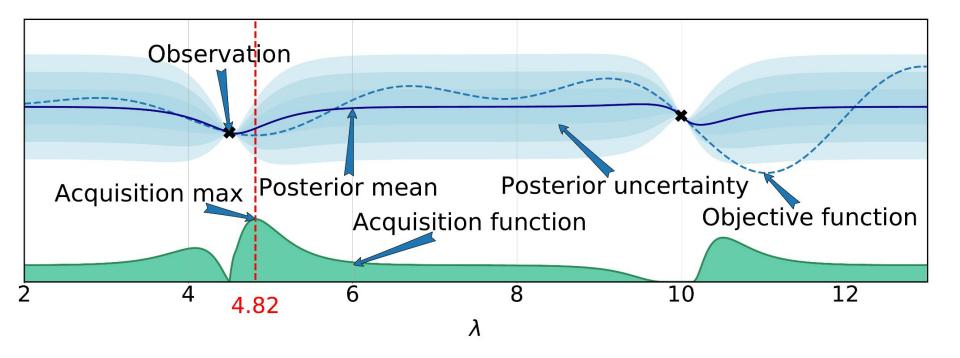














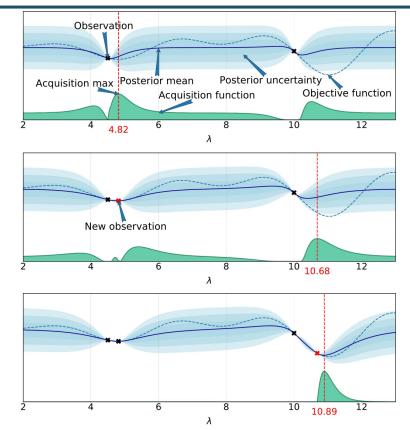
#### General approach

- Fit a probabilistic model to the collected function samples  $\langle \lambda, c(\lambda) \rangle$
- Use the model to guide optimization, trading off exploration vs exploitation

#### Popular approach in the statistics literature since Mockus et al. [1978]

- Efficient in #function evaluations
- Works when objective is nonconvex, noisy, has unknown derivatives, etc.
- Recent convergence results

[Srinivas et al. 2009; Bull et al. 2011; de Freitas et al. 2012; Kawaguchi et al. 2015]



(cc)

#### BO loop

**Require:** Search space  $\Lambda$ , cost function c, acquisition function u predictive model  $\hat{c}$ , maximal number of function evaluations T

**Result** : Best configuration  $\hat{\lambda}$  (according to  $\mathcal{D}$  or  $\hat{c}$ )

- 1 Initialize data  $\mathcal{D}^{(0)}$  with initial observations
- 2 for t=1 to T do

3 | Fit predictive model 
$$\hat{c}^{(t)}$$
 on  $\mathcal{D}^{(t-1)}$ 

- 4 Select next query point:  $\boldsymbol{\lambda}^{(t)} \in \arg \max_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} u(\boldsymbol{\lambda}; \mathcal{D}^{(t-1)}, \hat{c}^{(t)})$ 5 Query  $c(\boldsymbol{\lambda}^{(t)})$
- 6 Update data:  $\mathcal{D}^{(t)} \leftarrow \mathcal{D}^{(t-1)} \cup \{ \langle \boldsymbol{\lambda}^{(t)}, c(\boldsymbol{\lambda}^{(t)}) \rangle \}$



## Why is it called Bayesian Optimization?

• Bayesian optimization uses Bayes' theorem:

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)} \propto P(B|A) \times P(A)$$

- Bayesian optimization uses this to compute a posterior over functions:
  - $P(f|\mathcal{D}_{1:t}) \propto P(\mathcal{D}_{1:t}|f) \times P(f), \quad \text{where } \mathcal{D}_{1:t} = \{\lambda_{1:t}, c(\lambda_{1:t})\}$

Meaning of the individual terms:

- $\blacktriangleright$  P(f) is the prior over functions, which represents our belief about the space of possible objective functions before we see any data
- *D*<sub>1:t</sub> is the data (or observations, evidence)
  *P*(*D*<sub>1:t</sub>|*f*) is the likelihood of the data given a function
- $P(f|\mathcal{D}_{1:t})$  is the posterior probability over functions given the data



#### **Advantages**

- Sample efficient
- Can handle noise
- Priors can be incorporated
- Does not require gradients
- Theoretical guarantees

Many extensions available: Multi-Objective | Multi-Fidelity | Parallelization | Warmstarting | etc.

#### **Disadvantages**

- Overhead because of model training
- Crucially relies on robust surrogate model
- Has quite a few design decisions



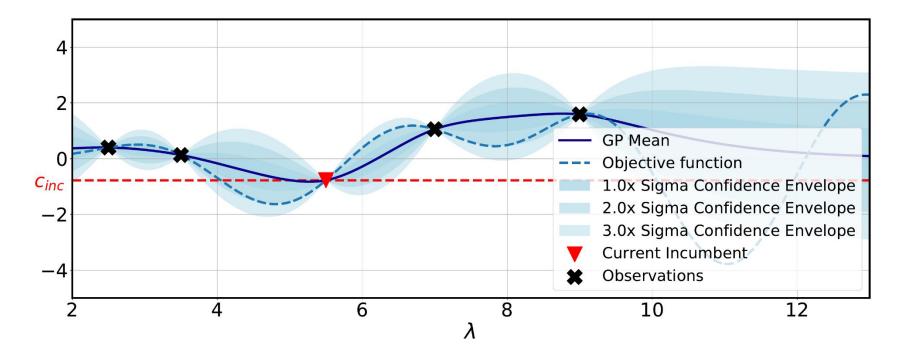
The acquisition function

- decides which configuration to evaluate next
- judges the **utility** (or **usefulness**) of evaluating a configuration (based on the surrogate model)

#### $\rightarrow$ It needs to trade-off exploration and exploitation

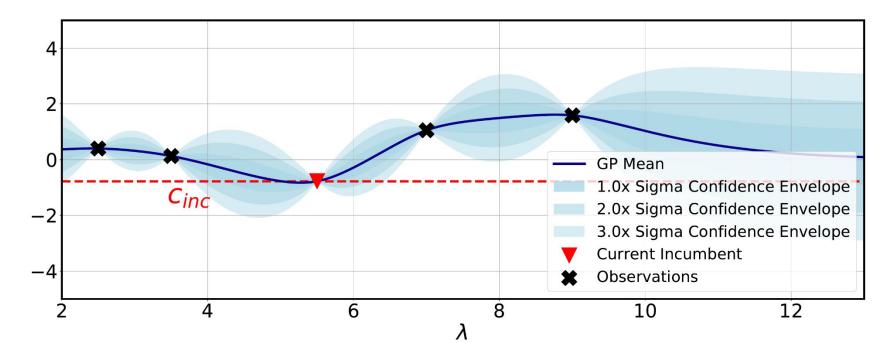
- Just picking the configuration with the lowest prediction would be too greedy
- It needs to consider the uncertainty of the surrogate model





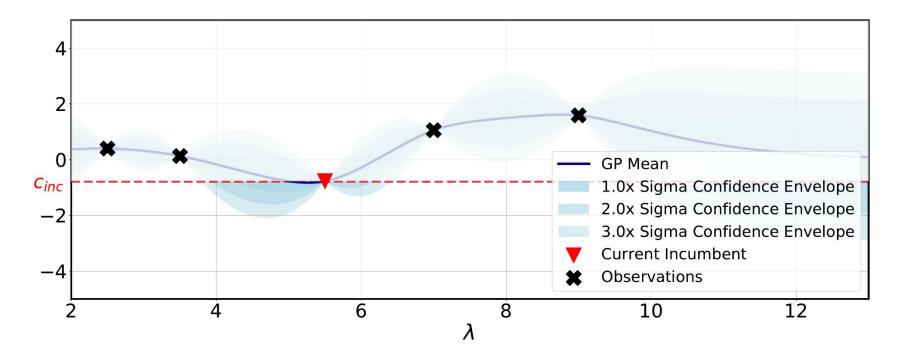
Given some observations and a fitted surrogate,





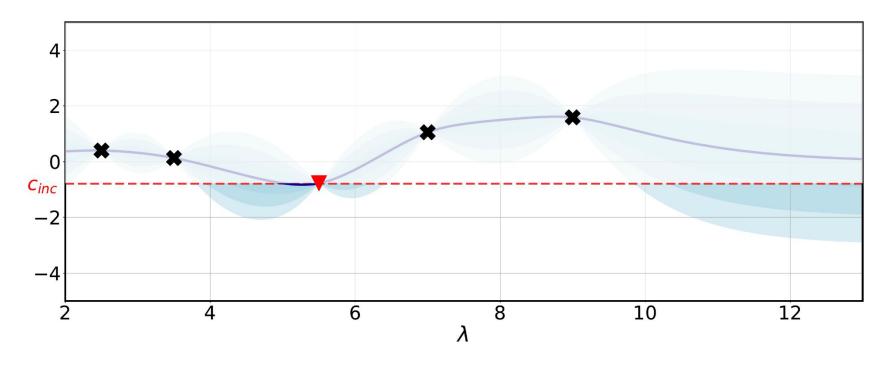
Given some observations and a fitted surrogate,





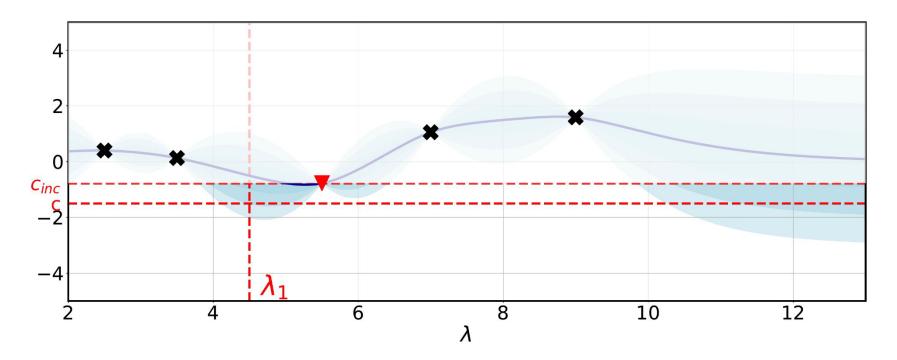
We care about *improving* over the c<sub>inc</sub>.





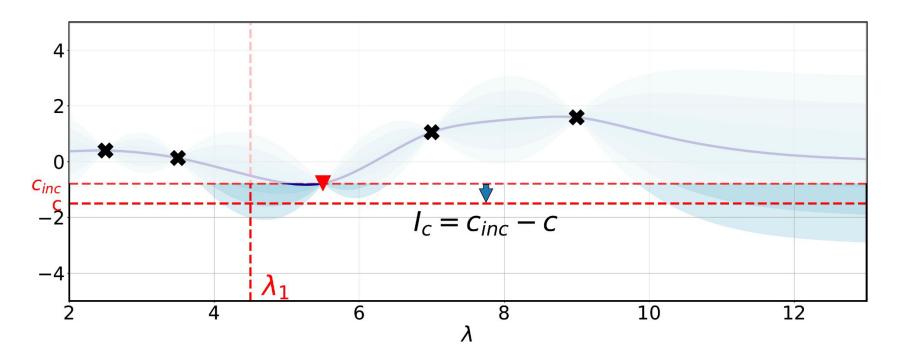
We care about *improving* over the  $c_{inc}$ .





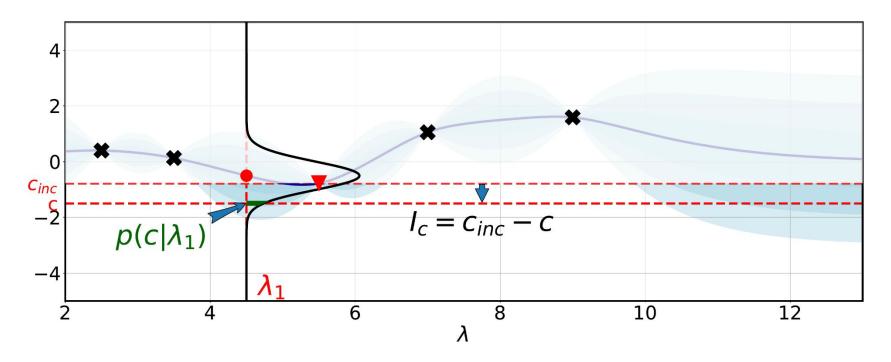
Let's look at a candidate configuration  $\lambda_1$  and its hypothetical cost c.





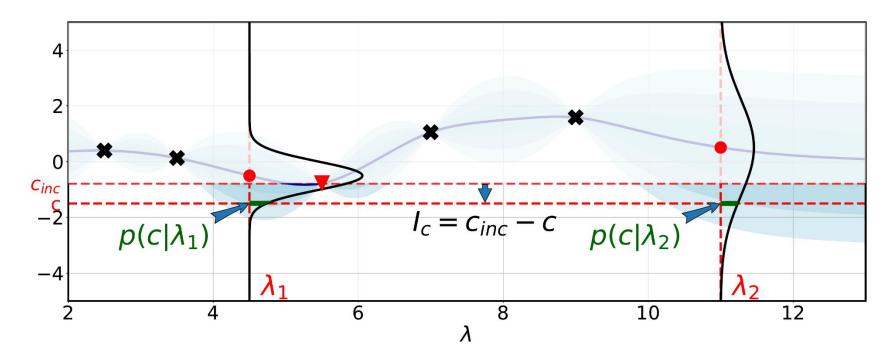
We can compute the improvement  $I_c(\lambda_1)$ . But how likely is it?





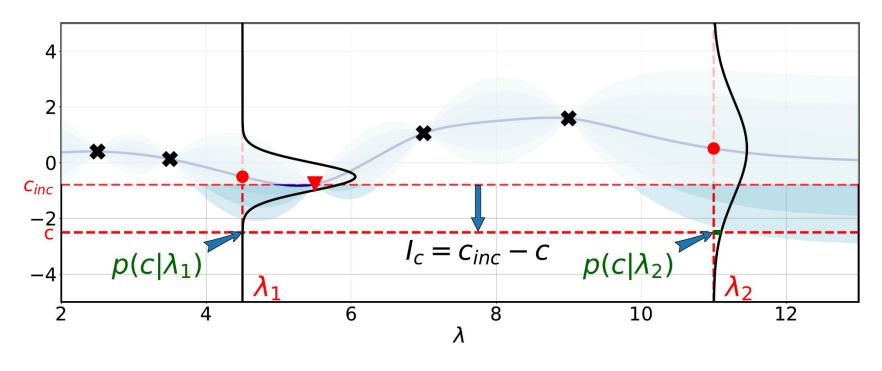
Knowing that  $\hat{c}(\boldsymbol{\lambda}) = \mathcal{N}(\mu(\boldsymbol{\lambda}), \sigma^2(\boldsymbol{\lambda}))$ , we can compute  $p(c|\boldsymbol{\lambda})$ 





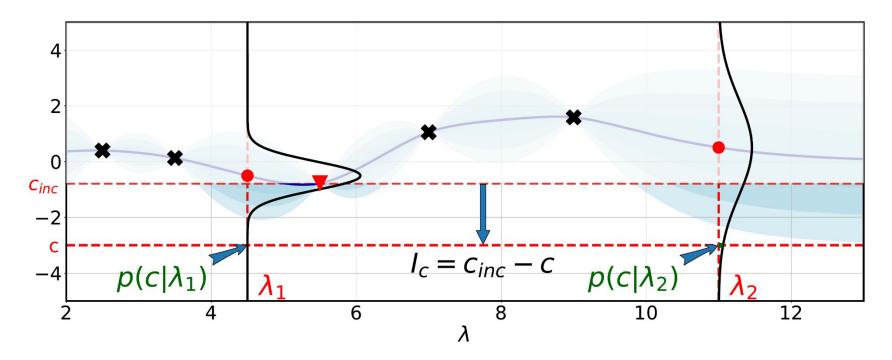
Comparing this for different configurations





and costs.





To compute EI, we sum all  $p(c \mid \boldsymbol{\lambda}) \times I_c$  over all possible cost values.



We define the one-step positive improvement over the current incumbent as

$$X^{(t)}(\boldsymbol{\lambda}) = \max(0, c_{inc} - c(\boldsymbol{\lambda}))$$

Expected Improvement is then defined as

$$u_{EI}^{(t)}(\boldsymbol{\lambda}) = \mathbb{E}[I^{(t)}(\boldsymbol{\lambda})] = \int_{-\infty}^{\infty} p^{(t)}(c \mid \boldsymbol{\lambda}) \times I^{(t)}(\boldsymbol{\lambda}) \ dc.$$

Since posterior is Gaussian, EI can be computed in closed form.

Choose 
$$\boldsymbol{\lambda}^{(t)} \in \operatorname*{arg\,max}_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}}(u^{(t)}_{EI}(\boldsymbol{\lambda}))$$

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#### **Other Acquisition Functions**

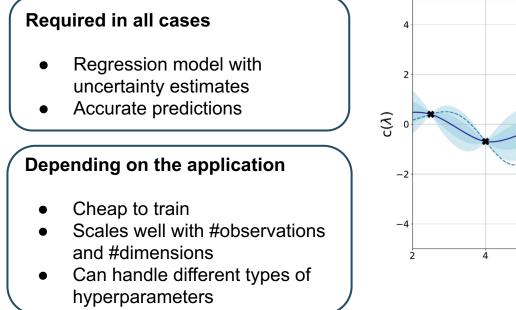
- Improvement-based policies [Expected Improvement (EI), Probability of Improvement (PI), and Knowledge Gradient]
- **Optimistic** policies [Upper/Lower Confidence Bound (UCB/LCB)]
- Information-based policies [Entropy Search (ES)]
  - aim to increase certainty about the location of the minimizer
  - not necessarily evaluate promising configurations
- Methods combining/mixing/switching these [Hoffman et al. 2011; Cowen-Rivers 2022]

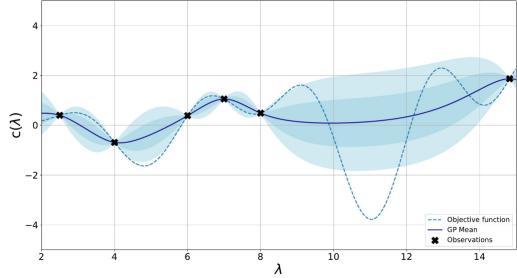




# Questions?

## Main Ingredient II: The Surrogate Model







## **Types of Surrogates Models**

Gaussian Processes

Random Forests



• Bayesian Neural Networks



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#### **Gaussian Processes**

 $\begin{aligned} m(\mathbf{x}) &= \mathbb{E}[f(\mathbf{x})] \\ k(\mathbf{x}, \mathbf{x}') &= \mathbb{E}\Big[ (f(\mathbf{x}) - \mathbb{E}[f(\mathbf{x})]) \left( f(\mathbf{x}') - \mathbb{E}[f(\mathbf{x}')] \right) \Big] \\ f(\mathbf{x}) \sim \mathcal{G} \left( m(\mathbf{x}), k(\mathbf{x}, \mathbf{x}') \right) \end{aligned}$ 

#### Advantages

- Smooth uncertainty estimates
- Strong sample efficiency
- Expert knowledge can be encoded in the kernel
- Accurate predictions

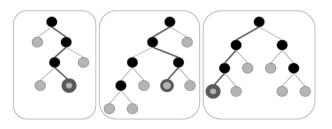
#### Disadvantages

- Cost scales cubically with #observations
- Weak performance for high dimensionality
- Not easily applicable in discrete, categorical or conditional spaces
- Sensitive wrt its own hyperparameters

→ These make GPs the most commonly used model for Bayesian optimization



#### **Tree-Based Methods**



#### Advantages

- Scales well with #dimensions and #observations
- Training can be parallelized and is fast
- Can easily handle discrete, categorical and conditional spaces
- Robust wrt. its own hyperparameters



#### **Disadvantages**

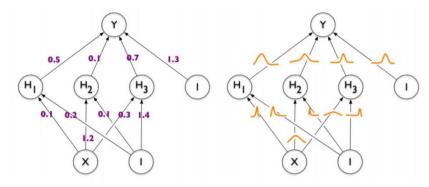
- Poor uncertainty estimates
- Poor extrapolation (constant)
- Expert knowledge can not be easily incorporated

→ These make RFs a robust option in high dimensions, a high number of evaluations and for mixed spaces

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#### **Bayesian Neural Networks**



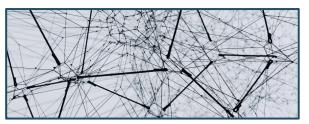


Image source: [Blundell et al. 2015]

#### **Advantages**

- Scales linear #observations
- (Can yield) smooth uncertainty estimates
- Flexibility wrt. discrete and categorical spaces

#### **Disadvantages**

- Needs many #observations
- Uncertainty estimates often worse than for GPs
- Many hyperparameters
- No robust off-the-shelf model

→ These make BNNs a promising alternative. [Li et al. 2023]

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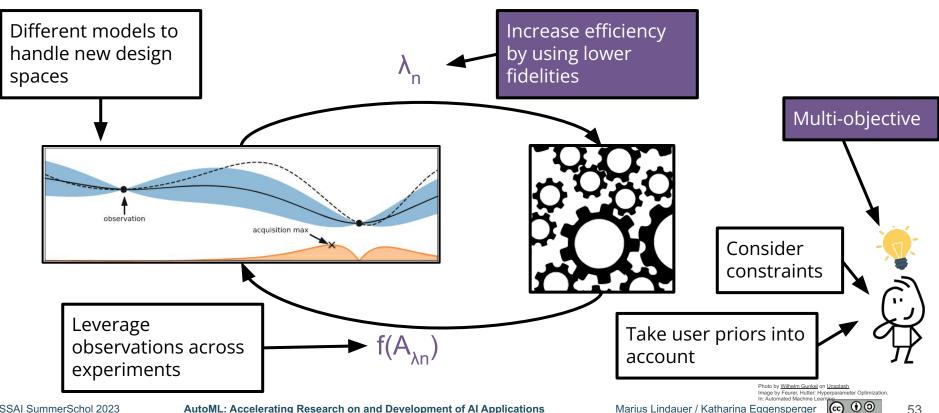
# Questions?

# Kahoot Quiz II

## How do we optimize it even more?

>> Here's my algorithm, data and design space, I have only limited time and I want more, what should I do?

#### **Bayesian Optimization: Extensions**



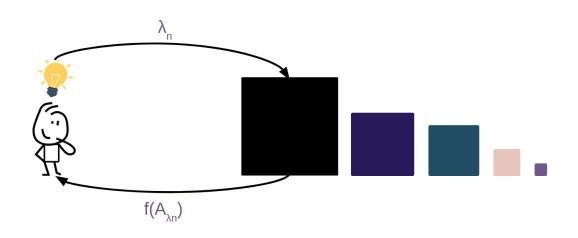
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AutoML: Accelerating Research on and Development of Al Applications

Marius Lindauer / Katharina Eggensperger



#### **Multi-Fidelity Bayesian Optimization**



Often, the black-box

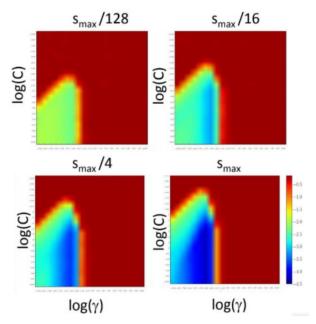
- is an iterative process,
- has cheaper approximations available,
- or can be evaluated partially

 $\rightarrow$  We can collect information about the actual objective value with less costly evaluations

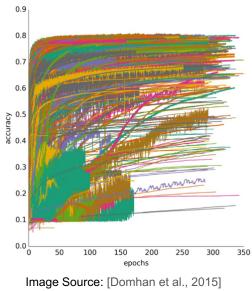


## **Two Motivating Examples**

## Performance of a SVM on different subsets of MNIST

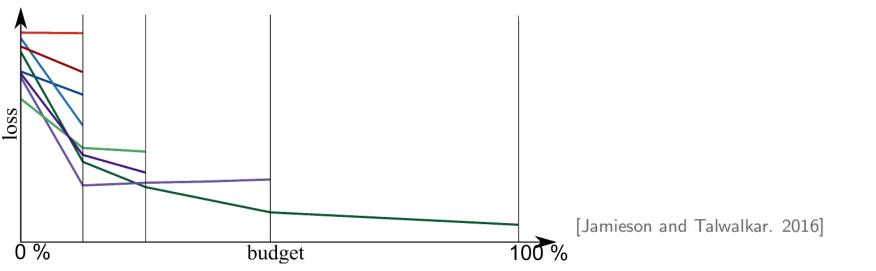


## Learning curves of fully connected NNs on CIFAR-10





## **Successive Halving**



• A very simple algorithm:

- Sample N configurations uniformly at random & evaluate them on the cheapest fidelity
- Keep the best half (or third), move them to the next fidelity
- Iterate until the most expensive fidelity (= original expensive black box)



What if the information on the lowest fidelity is not informative?

 $\rightarrow$  Run multiple iterations of SH, starting at different "lowest" fidelities.

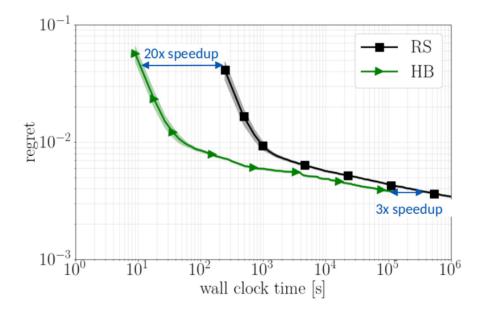


image credit: [Falkner et al. 2018]



## BOHB: Hyperband X Bayesian Optimization

Idea: Use Bayesian Optimization to choose configurations [Falkner et al. 2018]

- BO to achieve strong performance
- HB to achieve good anytime performance

 $\rightarrow$  easy parallelization

 $\rightarrow$  with interleaved random sampling it keeps theoretical guarantees of HB

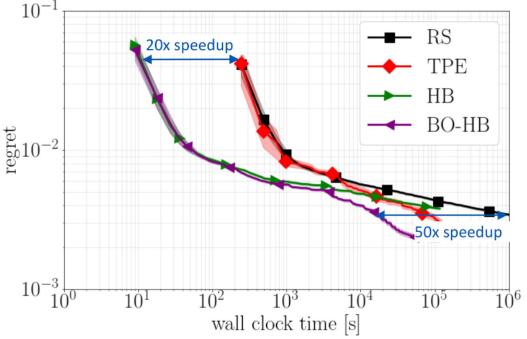
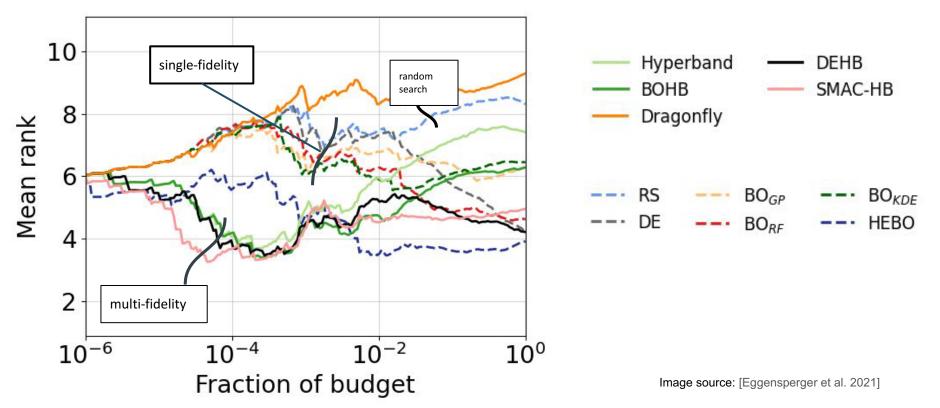


image credit: [Falkner et al. 2018]



#### Landscape of Multi-Fidelity HPO Methods

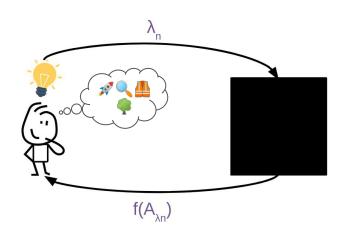






# Questions?

### **Multi-Objective Optimization**

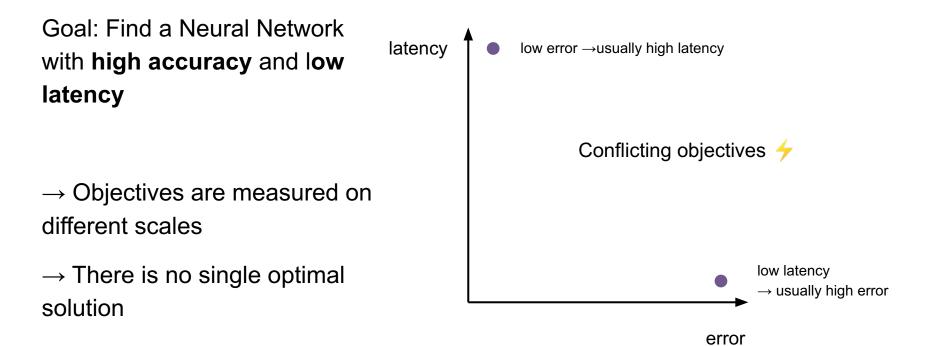


In practice, we often care about more than a single objective, e.g.

- error,
- inference time
- unfairness,
- energy consumption,
- model complexity,
- and many more



#### **Practical Example**





#### Definition

A multi-criteria optimization problem is defined by

$$\min_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} c(\boldsymbol{\lambda}) \Leftrightarrow \min_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} \left( c_1(\boldsymbol{\lambda}), c_2(\boldsymbol{\lambda}), ..., c_m(\boldsymbol{\lambda}) \right),$$

with  $\mathbf{\Lambda} \subset \mathbb{R}^n$  and multi-criteria objective function  $c : \mathbf{\Lambda} \to \mathbb{R}^m$ ,  $m \geq 2$ .

- Goal: minimize multiple target functions simultaneously.
- $(c_1(\boldsymbol{\lambda}), ..., c_m(\boldsymbol{\lambda}))^{\top}$  maps each candidate  $\boldsymbol{\lambda}$  into the objective space  $\mathbb{R}^m$ .
- W.I.o.g. we always minimize.
- Alternative names: multi-criteria optimization, multi-objective optimization, Pareto optimization.



#### Definition:

Given a multi-criteria optimization problem

$$\min_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} \left( c_1(\boldsymbol{\lambda}), ..., c_m(\boldsymbol{\lambda}) \right), \quad c_i : \boldsymbol{\Lambda} \to \mathbb{R}.$$

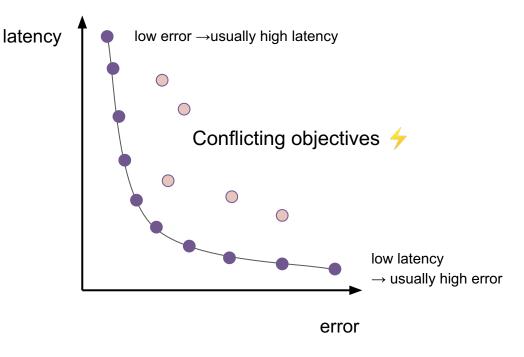
- A candidate  $\lambda^{(1)}$  (Pareto-) dominates  $\lambda^{(2)}$ , if  $c(\lambda^{(1)}) \prec c(\lambda^{(2)})$ , i.e.
  - **1**  $c_i(\boldsymbol{\lambda}^{(1)}) \leq c_i(\boldsymbol{\lambda}^{(2)})$  for all  $i \in \{1, 2, ..., m\}$  and
  - 2  $c_j(\boldsymbol{\lambda}^{(1)}) < c_j(\boldsymbol{\lambda}^{(2)})$  for at least one  $j \in \{1, 2, ..., m\}$
- A candidate  $\lambda^*$  that is not dominated by any other candidate is called **Pareto optimal**.
- The set of all Pareto optimal candidates is called **Pareto set**  $\mathcal{P} := \{ \boldsymbol{\lambda} \in \boldsymbol{\Lambda} | \not \exists \ \tilde{\boldsymbol{\lambda}} \text{ with } c(\tilde{\boldsymbol{\lambda}}) \prec c(\boldsymbol{\lambda}) \}$
- $\mathcal{F} = c(\mathcal{P}) = \{c(\boldsymbol{\lambda}) | \boldsymbol{\lambda} \in \mathcal{P}\}$  is called **Pareto front**.



#### **Practical Example**

Goal: Find a Neural Network with high accuracy and low latency

Goal: Find the Pareto Set of Neural Networks that balance accuracy and latency.





## Multi-Objective Bayesian Optimization

#### BO loop

Require: Search space  $\Lambda$ , cost function c, acquisition function u, predictive model  $\hat{c}$ , maximal number of function evaluations TResult : Best configuration  $\hat{\lambda}$  (according to  $\mathcal{D}$  or  $\hat{c}$ )1 Initialize data  $\mathcal{D}^{(0)}$  with initial observations2 for t = 1 to T do3 Fit predictive model  $\hat{c}^{(t)}$  on  $\mathcal{D}^{(t-1)}$ 4 Select next query point:  $\lambda^{(t)} \in \arg \max_{\lambda \in \Lambda} u(\lambda; \mathcal{D}^{(t-1)}, \hat{c}^{(t)})$ 5 Query  $c(\lambda^{(t)})$ 6 Update data:  $\mathcal{D}^{(t)} \leftarrow \mathcal{D}^{(t-1)} \cup \{\langle \lambda^{(t)}, c(\lambda^{(t)}) \rangle\}$ 

Two basic approaches:

- Simplify the problem by scalarizing cost functions
- Define a new acquisition function for multiple costs



#### Scalarization

Idea: Aggregate all cost functions

$$\min_{oldsymbol{\lambda}\inoldsymbol{\Lambda}}\sum_{i=1}^m w_i c_i(oldsymbol{\lambda}) \qquad ext{with} \quad w_i\geq 0$$

- Obvious problem: How to choose  $w_1, \ldots, w_m$ ?
  - Expert knowledge?
  - Systematic variation?
  - Random variation?
- If expert knowledge is not available a-priori, we need to ensure that different trade-offs between cost functions are explored.
- Simplifies multi-criteria optimization problem to single-objective
  —> Bayesian optimization can be used without adaption of the general algorithm.



### Scalarization: ParEGO

Scalarize the cost functions using the augmented Tchebycheff norm / achievement function

$$c = \max_{i=1,\dots,m} \left( w_i c_i(\boldsymbol{\lambda}) \right) + \rho \sum_{i=1}^m w_i c_i(\boldsymbol{\lambda}),$$

• The weights  $w \in W$  are drawn from

$$W = \left\{ w = (w_1, \dots, w_m) | \sum_{i=1}^m w_i = 1, w_i = \frac{l}{s}, l \in 0, \dots, s \right\},\$$

with  $|W| = {\binom{s+m-1}{k-1}}1.$ 

- New weights are drawn in every BO iteration.
- $\rho$  is a small parameter suggested to be set to 0.05.
- s selects the number of different weights to draw from.



#### ParEGO loop

- **Require:** Search space  $\Lambda$ , cost function c, acquisition function u, predictive model  $\hat{c}$ , maximal number of function evaluations T,  $\rho$ , l, s
- **Result** : Best configuration  $\hat{\lambda}$  (according to  $\mathcal{D}$  or  $\hat{c}$ )
- 1 Initialize data  $\mathcal{D}^{(0)}$  with initial observations
- 2 for t = 1 to T do

Sample w from 
$$\{w = (w_1, \dots, w_m) | \sum_{i=1}^m w_i = 1, w_i = \frac{l}{s} \land, l \in 0, \dots, s\}$$
  
Compute scalarization  $c^{(t)} = \max_{i=1}^m w_i c_i(\boldsymbol{\lambda}) + o \sum_{i=1}^m w_i c_i(\boldsymbol{\lambda})$ 

- 5 Fit predictive model  $\hat{c}^{(t)}$  on  $\mathcal{D}^{(t-1)}$
- 6 Select next query point:  $\lambda^{(t)} \in \arg \max_{\lambda \in \Lambda} u(\lambda; \mathcal{D}^{(t-1)}, \hat{c}^{(t)})$
- 7 Query  $c(\boldsymbol{\lambda}^{(t)})$
- 8 Update data:  $\mathcal{D}^{(t)} \leftarrow \mathcal{D}^{(t-1)} \cup \{ \langle \boldsymbol{\lambda}^{(t)}, c(\boldsymbol{\lambda}^{(t)}) \rangle \}$





# Questions?

# Kahoot Quiz III

## Demo: SMAC

>> Here's my algorithm, data and design space, I have only limited time and want to use Bayesian Optimization, what should I do?

#### Recommendations

- Literature
  - Bayesian Optimization
  - A Tutorial on Bayesian Optimization
- Bayesian Optimization Tools
  - SMAC3 (Colab Demo)
  - o <u>Optuna</u>
  - Syne-Tune
  - BoTorch



# Thanks. See you tomorrow!

ESSAI SummerSchol 2023

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